EN CE

akytec



MU210-412

Digital output module

User guide

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Contents

1. Introduction 3
1.1. Terms and abbreviations 3
1.2. Symbols and key words 3
1.3. Intended use 3
1.4. Limitation of liability 3
1.5. Safety 3
2. Overview 5
2.1. Basic features 5
2.2. Design and indication 5
3. Specifications 7
3.1. Specification 7
3.2. Operating conditions 7
4. Configuration and operation 9
4.1. Connection with akYtecToolPro 9
4.1.1. Connection over USB 9
4.1.2. Connection over Ethernet 9
4.2. Real time clock 10
4.3. Battery 11
4.4. Ethernet 11
4.4.1. Network parameters setting using service button 11
4.5. Modbus Slave 12
4.6. Data logging 12
4.7. Digital outputs 13
4.7.1. On / Off mode 13
4.7.2. Low frequency PWM generation 13
4.7.3. High frequency PWM generation 14
4.7.4. Pulse generator 14
4.7.5. Switch-on modes 14
4.7.6. Output operation on the capacitive load 15
4.7.7. Inductive load 16
4.7.8. Output safe state 16
4.8. NTP protocol 16
4.9. MQTT protocol 17
4.9.1. Basics 17
4.9.2. Implementation 17
4.10. SNMP protocol 19
4.10.1. Basics 19
4.10.2. Implementation 19
4.11. Password 19
5. Installation 20
5.1. Mounting 20
5.2. Wiring 20
5.2.1. General information 21
5.2.2. Digital outputs 22
5.2.3. Ethernet 22

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6. Factory settings restoration 24
7. Maintenance 25
8. Transportation and storage 26
9. Scope of delivery 27
Appendix A. Dimensions 28
Appendix B. Galvanic isolation 29
Appendix C. Battery replacement 30
Appendix D. Modbus application 31

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1 Introduction

1.1 Terms and abbreviations

akYtecToolPro – configuration software
Modbus – application layer messaging protocol for client/server communication between devices connected on different types of buses or networks, originally published by Modicon (now Schneider Electric), currently supported by an independent organization Modbus-IDA (*www.modbus.org*)
NTP – Network Time Protocol
MQTT – Message Queuing Telemetry Transport, publish-subscribe network protocol to transport messages between devices
SNMP – Simple Network Management Protocol, an Internet Standard protocol for collecting and organizing information about managed devices on IP networks and for modifying that information to change device behavior
PWM – pulse width modulation
RTC – real-time clock
UTC – Coordinated Universal Time, worldwide primary time standard

1.2 Symbols and key words

WARNING
WARNING indicates a potentially dangerous situation that could result in death or serious injuries.

CAUTION
CAUTION indicates a potentially dangerous situation that could result in minor injuries.

NOTICE
NOTICE indicates a potentially dangerous situation that could result in damage to property.

NOTE
NOTE indicates helpful tips and recommendations, as well as information for efficient and trouble-free operation.

1.3 Intended use

The device has been designed and built solely for the intended use described here, and may only be used accordingly. The technical specifications contained in this document must be observed.
The device may be operated only in properly installed condition.

Improper use

Any other use is considered improper. Especially to note:
– The device may not be used for medical applications.
– The device may not be used in explosive environment.
– The device may not be used in atmosphere in which there are chemically active substances.

1.4 Limitation of liability

Our company does not bear any responsibility with respect to breakdowns or damages caused by using the product in a manner other than described in the Manual or in violation of the current regulations and technical standards.

1.5 Safety

WARNING
Ensure the mains voltage matches the voltage marked on the nameplate. Ensure the device is provided with its own power supply line and electric fuse.

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WARNING
The device terminals may be under a dangerous voltage. De-energize the device before working on it. Switch on the power supply only after completing all works on the device.

NOTICE
Supply voltage may not exceed 48 V. Higher voltage can damage the device.
If the supply voltage is lower than 10 V DC, the device cannot operate properly but will not be damaged.

NOTICE
If the device is brought from a cold to a warm environment, condensation may form inside the device. To avoid damage to the device, keep the device in the warm environment for at least 1 hour before powering on.

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2 Overview

MU210-412 is an extension module with 24 digital outputs.
The module operates as a slave in Ethernet network with Modbus TCP protocol.
The device is intended for use in industrial automation for creation of decentralized control systems.
The module can be configured with the configuration software akYtecToolPro (free) over USB or Ethernet interface (Sect. 4). The software can be downloaded from our homepage *www.akYtec.de*.

2.1 Basic features

- 24 transistor outputs with pulse-width modulation option (Sect. 4.9)
- Device and outputs status indicators (Sect. 2.2)
- Dual Ethernet (Sect. 4.4, 5.2.4)
- Slave in Modbus network over Ethernet (Sect. 4.5)
- USB configuration interface (Sect. 4.1.1)
- Real-time clock (Sect. 4.2)
- Data logging and archiving (Sect. 4.7)
- DIN rail or wall mounting (Sect. 5.1)

2.2 Design and indication

The device is designed in a plastic case for DIN rail or wall mounting (Sect. 5.1).
Plug-in terminal blocks enable quick and easy replacement of the device.

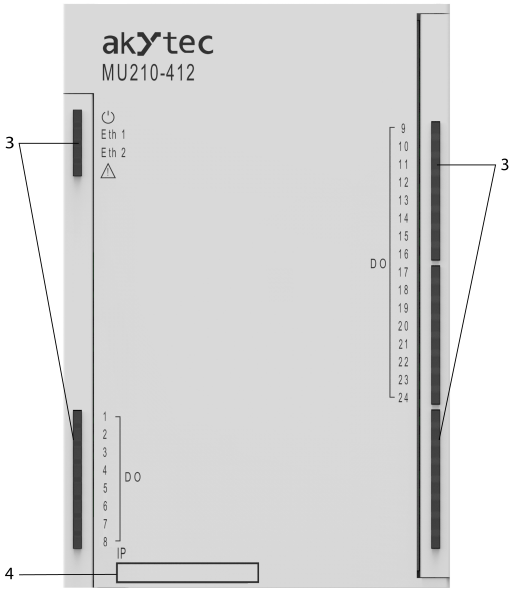


Fig. 2.1 Front view (closed cover)

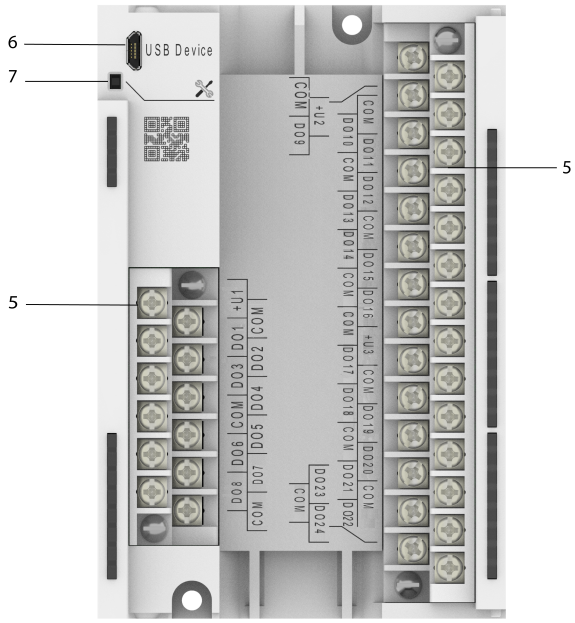


Fig. 2.2 Front view (open cover)

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On the device top:

1. Power supply terminals
2. 2 Ethernet connectors (Sect. 4.4, 5.2.4)

On the front cover:

3. LED indicators (Tab. 2.1)
4. Recess for a sticker with IP address

Under the front cover:

5. Removable terminal block (Sect. 5.2)
6. microUSB programming connector (Sect. 4.4.1)
7. Service button

The service button can be used for the following functions:

– IP address assignment (Sect. 4.1.1)
– Factory settings restoration (Sect. 6)

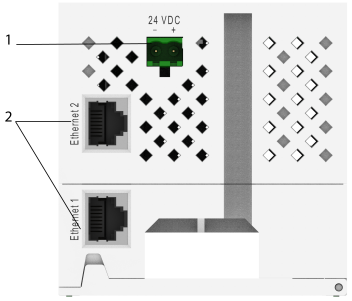


Fig. 2.3 Top view

Table 2.1 LEDs

LED	Color	LED State	Description
⏻	green	Off	Power off
		On	Power on
Eth 1	green	Off	Not connected
		Flashing	Data transfer over Ethernet 1 interface
Eth 2	green	Off	Not connected
		Flashing	Data transfer over Ethernet 2 interface
⚠	red	Off	No errors
		On	Program / configuration error
		Flashing (0.1 s / 2 s)	Low battery (Sect. 4.3, App. C)
		Flashing (0.1 s / 0.5 s)	No requests from master. Safe state activated
		Flashing (0.9 s / 1 s)	Hardware peripherals error (Flash, RTC, Ethernet Switch)
Output LEDs (8)	green	Off	Output off / Fault status
		On	Output on
	red	On	No output power supply

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3 Specifications

3.1 Specification

Table 3.1 General specifications

Electrical		
Power supply	24 (10 ... 48) V DC	
Power consumption	4 W at 24 V DC	
Polarity protection	Yes	
Appliance class	II	
Interfaces		
Data transfer	Double Ethernet 10/100 Mbps	
Protocols	Modbus TCP MQTT SNMP NTP	
Configuration interface	USB 2.0 (MicroUSB) Ethernet 10/100 Mbps	
Digital outputs		
Outputs number	24	
Output type	transistor	
Control	On-Off Low frequency PWM High frequency PWM Pulse generator	
Output switching mode	High-side switch (DO1-DO8)	Push-pull switch (DO9-DO24)
Output power supply	10…36 V	
DC load current, max.	0.15 A	0.4 A
Allowed short-time output current, max.	0.19 A	0.6 A
Output pulse length, max.	5 µs	1 ms
Output frequency (for resistive load), max.	60 kHz	1 Hz
Load capacity, max.	20 µF at <10 Hz	20 µF
Output protection	short circuit protection during power on output overcurrent protection	
Flash-memory (log file storage)		
File size, max.	2 kB	
Number of log files, ,max.	1000	
Logging interval, min.	10 s	
Real time clock		
Accuracy	±3 s/day at +25 °C ±10 s/day at -40 °C	
Backup battery	CR2032	
Mechanical		
Dimensions	42 × 124 × 83 mm	
Weight	approx. 600 g	

3.2 Operating conditions

The module is designed for natural convection cooling. It should considered when choosing the installation site.
The following environment conditions must be observed:

– clean, dry and controlled environment, low dust level
– closed non-hazardous areas, free of corrosive or flammable gases

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Table 3.2 Operating conditions

Condition	Permissible range
Ambient temperature Transportation and storage	-40…+55 °C
Relative humidity	up to 95 % (at +35 °C, non-condencing)
Attitude	up to 2000 m ASL
IP code	IP20
Vibration / shock resistance	conforms to IEC 61131-2
EMC emission / immunity	conforms to IEC 61131-2

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4 Configuration and operation

The device parameters can be set with akYtecToolPro or by command from a network Master.
The complete parameter list is presented in Appendix D. You can also read it out from the device using the toolbar item ***Parameter list*** in akYtecToolPro.
The modules of Mx210 series have the following parameter groups:

– Real-time clock (Sect. 4.2)
– Battery (Sect. 4.3)
– Network (Sect. 4.4)
– Modbus slave (Sect. 4.5)
– Device status (Sect. 4.6)
– Data logging (Sect. 4.7)
– I/O groups, depending on model (Sect. 4.8, 4.9)

4.1 Connection with akYtecToolPro

The connection with akYtecToolPro running on the PC can be established over the interfaces USB (Sect. 4.1.1) or Ethernet (Sect. 4.1.2).
For configuration over Ethernet, the device must be powered on. When being configured over USB, the device is powered by USB and the main power supply is not required.

4.1.1 Connection over USB

NOTICE
The device must be powered off before being connecting to PC over USB.

NOTICE
When the device is powered over USB, the inputs, outputs and the Ethernet interfaces are disabled. If you need full control over the device, you have to connect the main power, but you must observe the following:
There is no galvanic isolation between digital inputs and USB interface. Equipment connected to these circuits must have the same ground potential or be galvanically isolated to avoid damage to the device.

To configure the module over USB:

1. Connect the microUSB programming connector of the device (Fig. 2.2. Pos. 6) to PC over a USB-to-microUSB connection cable (not included).
2. Start akYtecToolPro.
3. In a new project, click the toolbar item ***Add devices*** .
4. In an opened dialog, select the interface ***STMicroelectronics Virtual COM Port.***
5. Select the protocol ***akYtec Autodetection Protocol.***
6. Select ***Find device.***
7. Enter the device address (factory setting: 1) and click ***Search.***
8. If the correct device is found, select it and click the button ***Add devices*** to add the device to the project.
9. If the device is password protected, enter the correct password.

If you forgot the password, restore the factory settings (Sect. 6).

4.1.2 Connection over Ethernet

To configure the module over Ethernet:

1. Connect the Ethernet connector of the device to PC over the Ethernet connection cable (not included).
2. Connect the power cable to the removable 2-terminal block and plug it into the device.
3. Power on the device.

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4. Start akYtecToolPro.
5. Click the toolbar item ***Add devices*** .
6. In the opened dialog select the interface ***Ethernet.***
7. Select ***Find device.***
8. Enter the IP address (Factory setting: 192.168.1.99) and click ***Search***.
9. If the correct device is found, select it and click the button ***Add devices*** to add the device to the project.
10. If the device is password protected, enter the correct password.

If you forgot the password, restore the factory settings (Sect. 6).

4.2 Real time clock

The module has a real-time clock (RTC) with a back-up battery (Sect. 4.3). The RTC time is counted as UTC in seconds, starting from 01/01/2000, 00:00.

To set the time, click the toolbar icon ***Real-time clock*** (Fig. 4.1).
Use the button ***Synchronize with PC*** to synchronize the RTC with the PC clock.
Select your time zone from the drop-down list below. You can also set the time zone in the range -720...+840 min. with a 60 min. step in the parameter group ***Real-time clock***.
Use the button ***Save*** to save the parameters in the device memory.

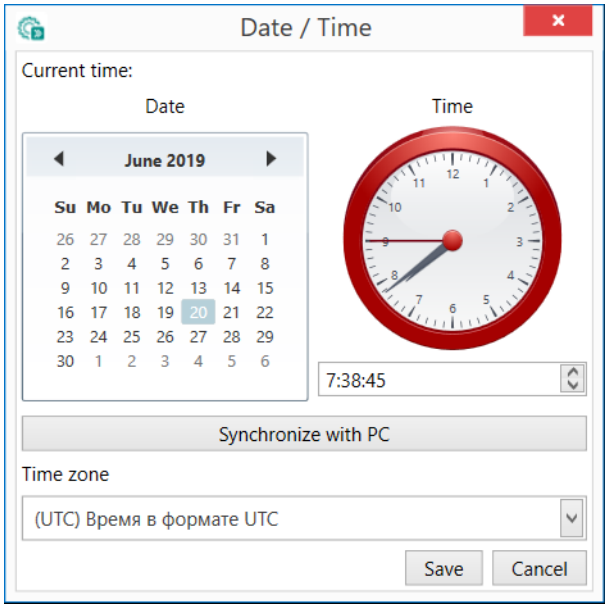


Fig. 4.1 Real-time clock parameters

The RTC is used for calculation of measuring timestamps (Sect. 4.8.5) and of ***Time (ms)*** parameter. ***Time (ms)*** is a cyclic time in milliseconds that starts with turning on and stops with turning off of the device. It is reset to zero at the end of cycle (4294967295 ms). The parameter is used for device diagnostic purposes.
To set the RTC time over Modbus network, proceed as follows:

1. Write the new time in the parameter ***New time.***
2. Set the parameter ***Apply new time*** = 1 and hold the value for at least 1 second.
3. Set the parameter ***Apply new time*** = 0 and hold the value for at least 1 second.

The time value cannot be changed more than once per second.

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4.3 Battery

The RTC is powered by the supply voltage. When the device is powered off, RTC is powered by a replaceable battery of type CR2032.
A fully charged battery can power the RTC for 5 years. At the temperatures near the permissible limits (Tab. 3.2), the battery life time is reduced.
The parameter ***Voltage*** in the group ***Battery*** shows the battery voltage in mV.
The battery status is updated each time after powering on and then every 12 hours.
The battery should be replaced if at least one of the following events has occurred:

– LED indicator ⚠ lights up for 0.2 s with a period of 2 s, which means that $U_B \leq 2$ V and the battery has to be replaced as soon as possible, but the RTC can still work for about 2 weeks without power supply.
– The battery was last time replaced 6 years ago.

For battery replacement, see App. C.

NOTE
If the battery voltage is less than 1.6 V, the configuration parameters are written to the battery-backed RAM and then transferred to the flash memory. The recording interval depends on the load of the module processor (at least 2 minutes).
Since the number of erase cycles of the flash memory is limited, it is not recommended to record the configuration parameters cyclically when the battery is low.

4.4 Ethernet

To configure the Ethernet interface, open the node ***Network > Ethernet*** in the parameter tree.

Table 4.1 Ethernet parameters

Parameter	Description	Default value	Access
IP address	IPv4 Internet Protocol address	192.168.1.99	R
Subnet mask	IP address recognition area in the subnet	255.255.255.0	R
Gateway	IP address of the gateway	192.168.1.1	R
DNS server 1	Primary DNS server	77.88.8.8	RW
DNS server 2	Secondary DNS server	8.88.8.8	RW
New IP address	Enter new value	—	RW
New subnet mask	Enter new value	—	RW
New gateway	Enter new value	—	RW
DHCP	***On*** / ***Off*** / ***Service button***	***Service button***	RW

The Ethernet parameters can be set using:

– only main toolbar
– service button on the device (recommended if you need to configure several devices at once) (Sect. 4.4.1.)

To change Ethernet parameters using the main toolbar:

1. Enter new values for the parameters ***New IP address***, ***New subnet mask*** and ***New gateway***
2. set the parameter ***DHCP*** to ***Off***
3. Click the toolbar item ***Write parameters*** 
4. Click the toolbar item ***Restart device*** 
5. If you want to check the new parameters or continue configuring the device, you must add it again to the project with the new network parameters.

If a dynamic IP address is required (e.g. to use a cloud service), set ***DHCP*** to ***On***.

4.4.1 Network parameters setting using service button

If you need to assign IP addresses for several modules, it is more comfortable to use service buttons on devices (Fig. 2.2. Pos. 7), previously having all the modules connected to the PC over Ethernet.

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To change the Ethernet parameters using service buttons:

1. Connect all modules in series to the PC over Dual Ethernet ports (Fig. 2.3. Pos. 2)
2. Power on the modules
3. Start akYtecToolPro
4. Set the parameter ***DHCP*** to ***Service button*** on all modules
5. Click the toolbar item ***IP addresses*** IP
6. Set the IP address for the first module from the group
7. Press the service buttons on the modules sequentially, checking the result in the dialog box, where will be indicated on which module the button was pressed. The specified static IP address and other network parameters, if any have been changed, are assigned to this module. The address is automatically incremented by 1 for each subsequent device.

Only Ethernet parameters will be changed, other parameters will not be affected.
If you forgot the IP address, you can find it in akYtec Tool Pro by connecting the module to your computer using USB.

4.5 Modbus Slave

The module can operate in Modbus TCP network as a slave, using the port 502 and the standard address 1. The address can be changed in the group ***Modbus Slave*** (Tab. 4.2).
The device can handle maximum 4 Modbus TCP connections.
For details on Modbus working see Appendix D.
For Modbus protocol specifications see *Modbus specifications*.

Table 4.2 Modbus Slave parameters

Parameter	Description	Range	Default value	Access
Slave address	Device address in a Modbus network	1…254	1	RW
Safe state timeout	Output safe state activation delay after communication interruption (Sect. 4.9.1)	0…60 s	30	RW

4.6 Data logging

An archive is saved as a set of encrypted log files. A log file consists of a set of records separated by line break characters (0x0A0D). Each record corresponds to one parameter and consists of fields separated by semicolon. The format of the record is described in Tab. 4.4.

Table 4.3 Record format

Field	Type	Size	Comment
Time	binary	4 Byte	In seconds, beginning from 01/01/2000, 00:00 (UTC+0)
Separator	string	1 Byte	Semicolon (;)
UID (parameter ID)	string	8 Byte	String of HEX characters with leading zeros
Separator	string	1 Byte	Semicolon (;)
Parameter value	string	parameter depending	String of HEX characters with leading zeros
Separator	string	1 Byte	Semicolon (;)
Parameter status	binary	1 Byte	1 – value correct 0 – value incorrect, further processing not recommended
New line	binary	2 Bytes	0x0A0D

Log files are stored in a built-in flash memory, formatted as a file system with encryption. For flash memory specifications see section “Flash memory” in Table 3.1.
If an archive overflows, the new entry will overwrite the oldest one in the archive.
The archiving parameters are described in Tab. 4.5.
To view all logged parameters, use the toolbar item ***Device information*** in akYtecToolPro.
The archive can be read with via Modbus TCP using function 20 (Tab. D.3). This function allows reading one or several records from one or several files in one request. For details on function usage see *Modbus specifications*.

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The file number in the Modbus request should be calculated as file ID + 4096. File indexing starts with zero. The parameter ***Last log file ID*** contains the ID of the archive file to which the data was last written.
The time zone is not contained in the file but can be read from the parameter ***Time zone*** (Tab. D.1).

Table 4.4 Archiving parameters

Parameter	Description	Range	Default value	Access
Logging interval	Time interval with which the values of the selected parameters will be recorded	10…3600 s	30	RW
Number of files	Maximum number of archive files	10…300	100	RW
File size	Log file size in Bytes	200…2048	2048	RW
Last log file ID	ID of the last written file	0…65535	—	R

4.7 Digital outputs

To configure the digital outputs, open the ***Digital outputs*** group in the parameter tree.

Table 4.5 Output parameters

Parameter	Description	Range	Default value	Access
Single				
Control	Output control mode	***On-Off*** / ***Low frequency PWM*** / ***High frequency PWM*** / ***Pulse generator***	***On-Off***	RW
Low frequency PWM period	Period in Low Frequency PWM mode	1000…6000 ms	100	RW
PWM duty cycle	Duty cycle in PWM mode	0…1000 ‰	50	RW
Pulse generator frequency	Frequency of pulses to generation	1…60000 Hz	1 Hz	RW
Pulse generator value	Number of pulses to generation	0…65535	0	RW
Safe state	Output state after communication loss	0…1000 ‰	0	RW
High frequency PWM frequency	Frequency in High Frequency PWM mode	1…60000 Hz	100	RW
Group				
Output bitmask	Output state bitmask	0…16777215	—	R
New outputs bistmask	New output state bitmask	0…16777215	0	RW

There are four modes of output control:
– On-off
– Low frequency pulse-width modulation (PWM)
– High frequency pulse-width modulation (PWM) (only DO1-DO8)
– Pulse generator (only DO1-DO3)

4.7.1 On / Off mode

Outputs in the **On / Off mode** are controlled by writing the bit mask of the output status to the corresponding Modbus registers.

4.7.2 Low frequency PWM generation

The module outputs can operate in the PWM signal generation mode.
To set the mode, you should set the parameter values
– PWM period (1000 to 60,000 ms);
– PWM duty cycle (%).

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4.7.3 High frequency PWM generation

Outputs DO1-DO8 can operate in the mode of generating high-frequency PWM signals.
To set the mode, you should set the parameter values:

– pulse repetition rate (from 0 to 60 kHz)
– PWM duty cycle (%)

4.7.4 Pulse generator

Outputs DO1-DO3 can operate in the mode of generating a given number of pulses.
Each output is controlled by writing parameter values to the output control registers:

– number of pulses (1…65535);
– pulse generator frequency (up to 60 kHz)

The generation of pulses begins after the number of pulses is written to the register ***Number of pulses to generate***. The duty cycle of the signal is unchanged and equal to 50%.
The ***Number of left pulses*** register for a particular output stores the number of pulses left to be delivered to the oscillator for that output.
To forcibly stop the generation of pulses, write the value **0** to the register ***Number of pulses to generate***.

4.7.5 Switch-on modes

Outputs DO1–DO8 operate in high-side switching mode. Outputs DO9–DO24 operate in the push-pull switching mode.

– high-side switch (*Fig. 4.2*) — for switching loads with lower capacitance and higher current
– push-pull switch (*Fig. 4.3*) — for switching loads with larger capacitance and lower current (less than 100 mA)

NOTE
It is not possible to change the activation mode of the outputs.

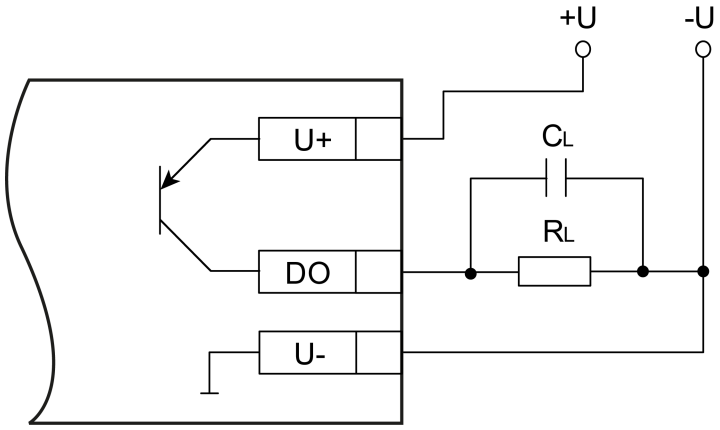


Fig. 4.2 Output wiring in high-side switching mode

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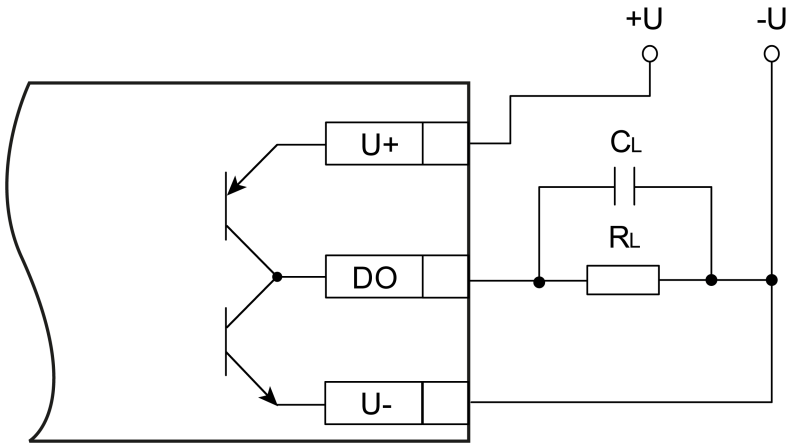


Fig. 4.3 Output wiring in push-pull switching mode

NOTE
In the high-side switching mode, in order to increase the load current, it is allowed to connect the load in parallel to several outputs of one group.

4.7.6 Output operation on the capacitive load

Module outputs can be connected to a capacitive load. Depending on the nominal value of the capacitance, restrictions are imposed on the maximum frequency and on the minimum pulse duration of the output signal.

4.7.6.1 High side switching mode

The minimum pulse duration at a supply voltage of 24 V outputs, depending on the resistive and capacitive load, is given in the *table 4.6*:

Table 4.6 Minimum duration of the output signal pulse in the high-side switching mode (μs)

Load resistance, R_L	Load capacity, C_L					
	0 pF	1000 pF	22 nF	50 nF	100 nF	1 μF
50 Ω	10	10	15	25	40	—
500 Ω	10	10	30	50	400	1500
5 kΩ	10	20	300	500	5000	10000

NOTE
* With a load capacity of 1 μF and a load resistance of 5 kΩ:
– maximum pulse rise time is 10 μs,
– maximum pulse decay time is 20 μs

The maximum allowable frequency of the PWM at the outputs supply voltage of 24 V when operating at resistive and capacitive loads is given in *table 4.7*:

Table 4.7 Maximum allowable PWM frequency (Hz)

Load resistance, R_L	Load capacity, C_L					
	0 pF	1000 pF	22 nF	50 nF	100 nF	1 μF
50 Ω	10 000	1 000	650	400	250	—
500 Ω	10 000	1 000	300	200	25	5
5 kΩ	10 000	500	30	20	2	1

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4.7.6.2 Push-pull switching mode

The minimum pulse duration at the outputs supply voltage of 24 V, depending on the resistive and capacitive loads, is given in *Table 4.8* below:

Table 4.8 Minimum pulse duration of the output signal in the push-pull output mode (µs)

Load resistance, R_L	Load capacity, C_L					
	0 pF	1000 pF	22 nF	50 nF	100 nF	1µF
250 Ω	1	1	2	4	10	—
500 Ω	1	1	3	6	20	80
5 kΩ	1	1	4	10	30	100*

* With a load capacity of 1 µF and a load resistance of 5 kΩ:
– maximum pulse rise time is 10 µs,
– maximum pulse decay time is 20 µs

The maximum allowable frequency of the PWM at the outputs supply voltage of 24 V when operating at resistive and capacitive loads is given in *Table 4.9*:

Table 4.9 Maximum allowable PWM frequency (Hz)

Load resistance, R_L	Load capacity, C_L					
	0 pF	1000 pF	22 nF	50 nF	100 nF	1µF
250 Ω	60,000	50,000	14,000	6,000	3,000	200
500 Ω	60,000	60,000	31,000	13,500	6,500	500
5 kΩ	60,000	60,000	50,000	35,000	17,000	1 000

4.7.7 Inductive load

Module outputs can be connected to an inductive load. The module implements hardware protection against self-induction current that occurs during load shedding. An external protective diode connection is not required.

4.7.8 Output safe state

A safe state can be set for each output. The output goes to a safe state if there are no commands from the Network Master during the timeout.
Safe state can be specified in the parameter ***Safe state*** for each output.
Safe state is inactive if the parameter ***Safe state timeout*** is set to 0.

4.8 NTP protocol

The module supports the synchronization of the RTC with an NTP server v4. Open the ***NTP*** group to configure NTP parameters.

Table 4.10 NTP parameters

Parameter	Description	Range	Default value	Access
Enable	Enable NTP connection	***On*** / ***Off***	***Off***	RW
NTP server pool	IP or URL of NTP pool. If the server is located in an external network, check the correct values for the parameters ***Gateway*** and ***DNS*** (***Network*** group)	—	pool.ntp.org	RW
NTP server 1	IP or URL of the primary NTP server	—	192.168.1.1	RW
NTP server 2	IP or URL of the secondary NTP server	—	192.168.1.2	RW

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Parameter	Description	Range	Default value	Access
Synchronization period	Time synchronization period in seconds. Ensure the set value is not less than the minimum value for the selected NTP server	5…65535 s	5	RW
Status	Server connection status	—	—	R

All specified NTP servers (including servers from the pool) have the same polling priority.
For more information see document: *NTP_MQTT_SNMP_protocols*.

4.9 MQTT protocol

4.9.1 Basics

The MQTT protocol defines two types of network entities: a message ***broker*** and a number of clients. Broker is a server that receives all messages from the clients and then routes the messages to the appropriate destination clients. Client can be ***publisher*** or / and ***subscriber***.
Published messages are organized in a hierarchy of ***topics***. When a publisher has a new data to distribute, it sends a message with the data under the particular topic to the connected broker. The broker distributes the message to any clients that have subscribed to that topic.
A topic is a UTF-8 encoded character string that the broker uses to filter messages for each connected client. The topic consists of one or more topic ***levels***. Each topic level is separated by a forward slash (topic level separator).
When a client subscribes to a topic, it can subscribe to the exact topic of a published message or it can use wildcards to subscribe to multiple topics simultaneously. There are two kinds of wildcard symbols: ***single-level*** (+) and ***multi-level*** *(#) (see* ***Example****)*.

4.9.2 Implementation

The module supports the MQTT protocol (v3.1.1) and can be used as client. It can publish information about the status of its inputs and outputs and can be subscribed to topics which control its outputs.
To configure the MQTT parameters, open the ***MQTT*** group in the parameter tree.

NOTE
When using the MQTT protocol, it is recommended to set the parameter "Safe state timeout" ("Modbus Slave" group) to 0, since writing is usually event-driven and not cyclic in this case.

Table 4.11 MQTT parameters

Parameter	Description	Range	Default value	Access
Presence detection. Enable	If ***On***, the module publishes the message "Online" to the topic specified in the parameter ***Topic name*** after switching on. If no messages are received from the module, the broker publishes an "Offline" message in this topic.	***On*** / ***Off***	***Off***	RW
Presence detection. Topic name	Topic name used for presence detection.	—	***MQTT status***	RW
Connect to broker	Set to ***On*** to establish connection	***On*** / ***Off***	***Off***	RW
User name	Used for device authentication on the broker side. Authentication is not used if the values are not specified.	—	—	RW
Password		—	—	RW
Device name	Device name used in the topic name (see Example)	—	—	RW
Broker address	Broker IP or URL. If the broker is located in an external network, check the correct values for the parameters ***Gateway*** and ***DNS*** (***Network*** group)	—	—	RW

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Parameter	Description	Range	Default value	Access
Port	Port for broken	0…65535	1883	RW
Store last message	If ***On***, other clients subscribed to the module's topics will receive the latest messages from these topics.	***On*** / ***Off***	***Off***	RW
Publishing interval	Publishing interval in seconds	5…600	10	RW
Quality of service	***QoS0*** - at most once ***QoS1*** - at least once ***QoS2*** - exactly once	***QoS0*** / ***QoS1*** / ***QoS2***	***QoS0***	RW
Keep Alive	Keep Alive interval in seconds	0…600	0	RW
Status	Broker connection status	—	—	R

Table 4.12 Topics

Parameter	Topic	Node	Function	Format
New output bitmask	MASK	DO	SET	UINT
Output bitmask	STATE	DO	GET	UINT

Example:
Device – device name specified in akYtecToolPro

1. Read the digital inputs bitmask

   MX210/Device/GET/DI/MASK

   Obtained value: 15 (HIGH on inputs 1-4)

2. Write the digital outputs bitmask

   MX210/Device/SET/DO/MASK

   Recorded value: 15 (outputs 1-4 set)

3. Single-level wildcard usage

   MX210/Device/GET/+/COUNTER

   Obtained value: counter values of all digital inputs. The topic is equivalent to the group of topics:

   MX210/Device/GET/DI1/COUNTER

   MX210/Device/GET/DI2/COUNTER

   MX210/Device/GET/…/COUNTER

   MX210/Device/GET/DIn/COUNTER

4. Multi-level wildcard usage

   MX210/Device/GET/#

   Obtained value: all module parameters available for reading. The topic is equivalent to a group of topics:

   MX210/Device/GET/DI/MASK

   MX210/Device/GET/DI1/COUNTER

   MX210/Device/GET/DI2/COUNTER

   MX210/Device/GET/…/COUNTER

   MX210/Device/GET/DIn/COUNTER

For more information see document: *NTP_MQTT_SNMP_protocols*.

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4.10 SNMP protocol

4.10.1 Basics

The protocol is based on the Client / Server architecture, where clients are called ***managers*** and servers are called ***agents***.
Managers can read (GET) and write (SET) agent parameters. Agents can send messages (***traps***) to managers about changes in any parameter.
Each agent parameter has a unique identifier (OID – object identifier), which is a sequence of numbers separated by periods.

4.10.2 Implementation

The module supports SNMP protocol (SNMPv1 and SNMPv2c versions) and can be used as an agent with GET and SET requests.
All module parameters are available via SNMP protocol. The list of parameters is given in App. D.

NOTE
When using the SNMP protocol without GET requests, it is recommended to set the parameter "Safe state timeout" (Modbus Slave group) to 0, since writing is usually event-driven and not cyclic in this case.

Table 4.13 SNMP parameters

Parameter	Description	Range	Default value	Access
Enable	Enable SNMP connection	***On*** / ***Off***	***Off***	RW
Read community	Password for read access	—	***public***	RW
Write community	Password for write access	—	***private***	RW
Trap IP address	IP address to which the trap will be sent in case of changing the mask of the digital inputs (modules with digital inputs only)	—	10.2.4.78	RW
Trap port	Port number to which the trap will be sent	0…65535	162	RW
SNMP version	Protocol version	***SNMPv1*** / ***SNMPv2***	***SNMPv1***	RW

For more information see document: *NTP_MQTT_SNMP_protocols*.

4.11 Password

You can use password to protect the configuration parameters of the device from an unauthorized access. To set the password, use the toolbar item ***Password*** or the same item in the device context menu. There is no password by default.
If you forgot the password, restore the factory settings (Sect. 6).

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5 Installation

The safety requirements from the section 1.5 must be observed.

5.1 Mounting

The device is designed to be installed on DIN rail or using two screws on a mounting panel in an electric cabinet.
The operating conditions from the Sect. 3.2 must be considered when choosing the installation site.
Dimensional drawings are given in Appendix A. Only the vertical positioning of the device is allowed.

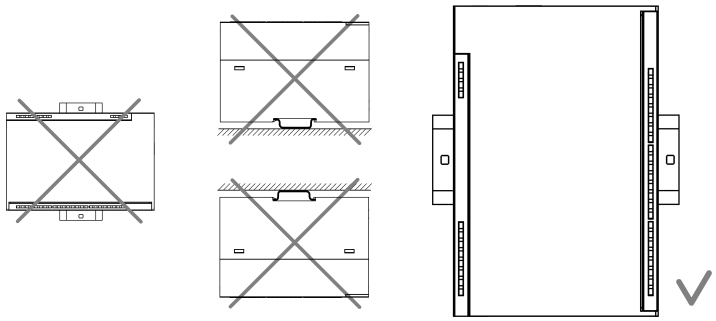


Fig. 5.1 DIN rail mounting

Device replacement (Fig. 5.2):

- switch off the power supply of the module and all connected devices
- open the front cover 1
- loosen the two screws 3
- remove the terminal block 2

Now you can replace the device.
Reverse this procedure after replacing the device.

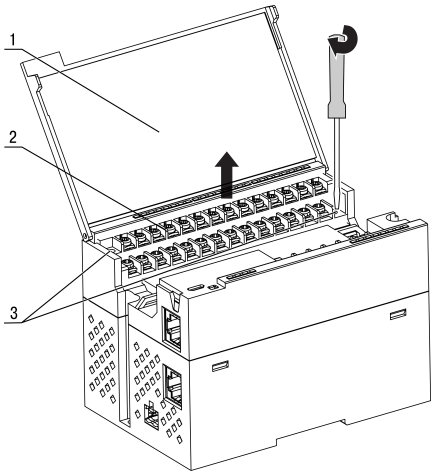


Fig. 5.2 Remove terminal block

5.2 Wiring

WARNING
The device must be powered off before connecting to peripheral equipment or PC. Switch on the power supply only after the wiring of the device has been completed.

NOTICE
Ensure that the input signal is connected to the correct input terminals and that the input configuration corresponds to the signal. Non-observance can cause the device damage.

NOTE
To ensure compliance with the EMC requirements:

- ***Signal cables should be routed separately or screened from the supply cables.***
- ***Shielded cable should be used for the signal lines.***

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5.2.1 General information

Power supply terminals and Ethernet interfaces are placed on the top of the device (Fig. 2.3. Pos. 1). Mating plug for the power supply is included.
Terminal assignments are given in Fig. 5.3 and Tab. 5.1.
Maximum conductor cross-section is 1.0 mm².
Plug-in terminal block for power supply and removable terminal block for output connections enable quick and easy replacement of the device (see Fig. 5.2).
When wiring is completed, the wires should be placed in a special recess under the cover so that adjacent devices can be placed on the DIN rail close to each other.

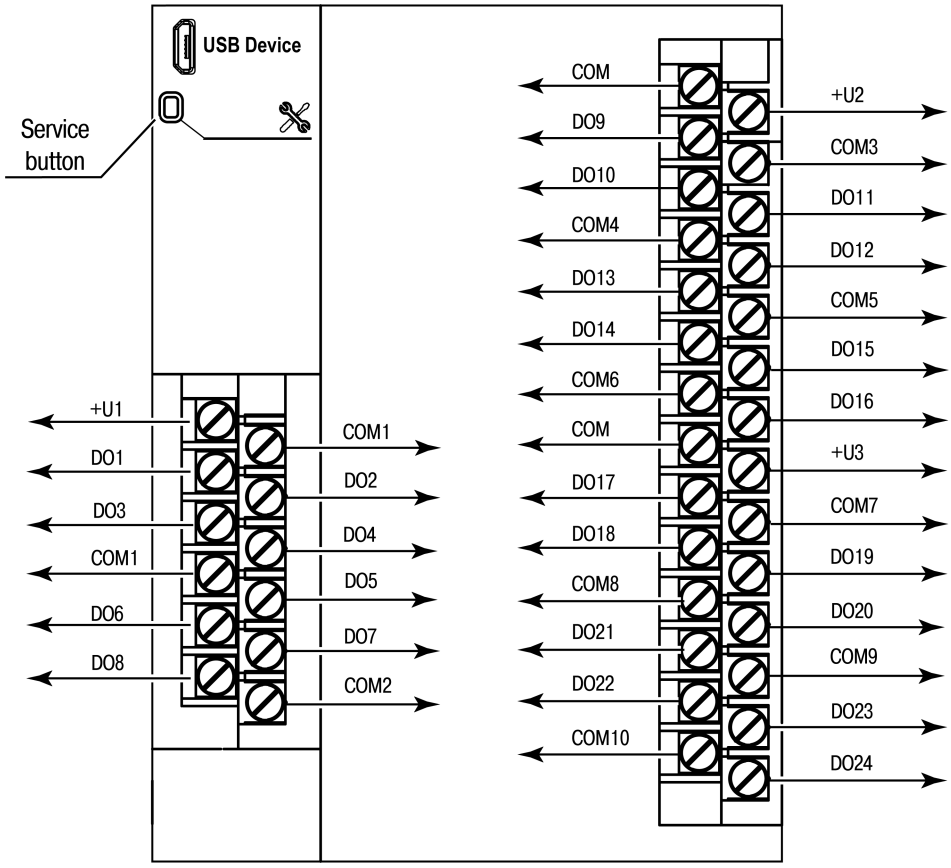


Fig. 5.3 Front view (open cover)

Table 5.1 Terminal assignments

Marking	Description
DI1…DI24	Input terminals
COM	Common input power supply point
+U1	Supply voltage for outputs DO1–DO8
+U2	Supply voltage for outputs DO9–DO16
+U3	Supply voltage for outputs DO17–DO24

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5.2.2 Digital outputs

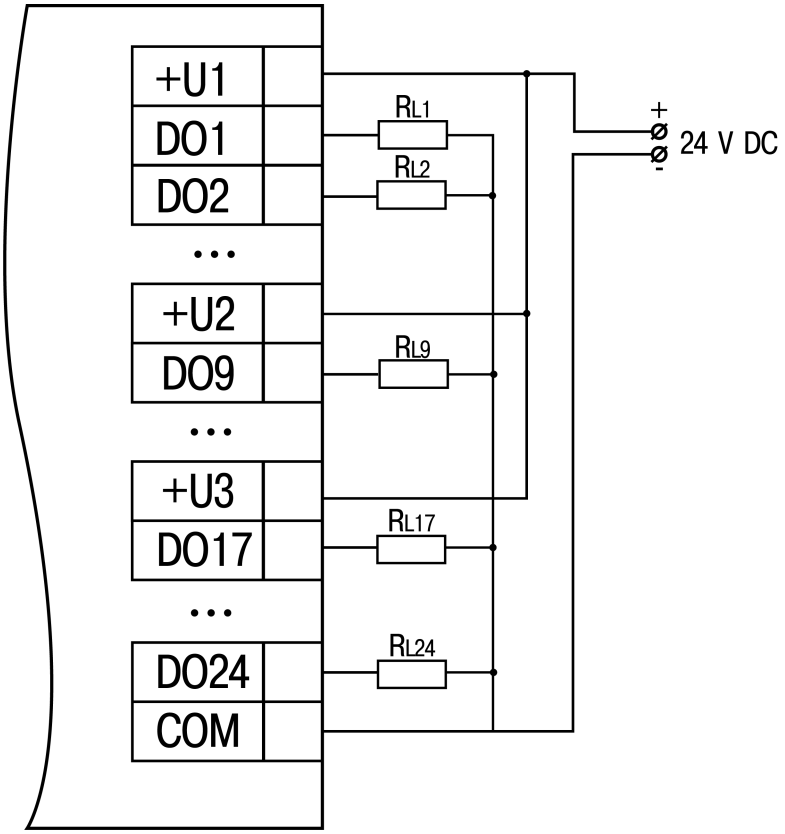
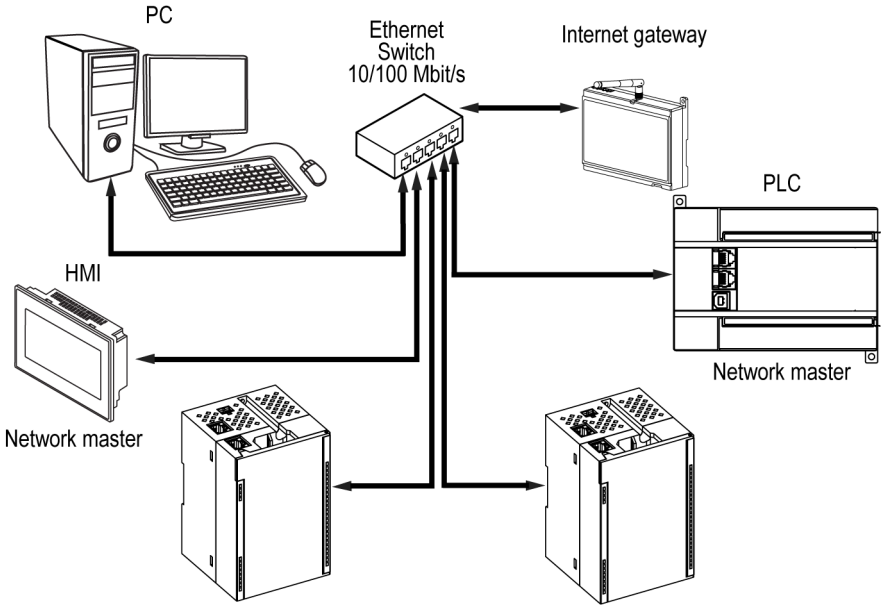


Fig. 5.4 DO wiring

5.2.3 Ethernet

The Ethernet connection can be established in a star or daisy chain topology (Fig. *5.5*, *5.6*).
It is recommended to seal the unused connector with a rubber plug (included).
Star topology:

– The maximum length of the network lines between modules is 100 m.
– Both Ethernet connectors can be used.



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Fig. 5.5 Star topology

Chain topology:

– maximum section length is 100 m
– realized with two Ethernet connectors
– If the module fails (device error or power supply loss), the data is transferred directly from connector 1 to connector 2 (auto-bypass).

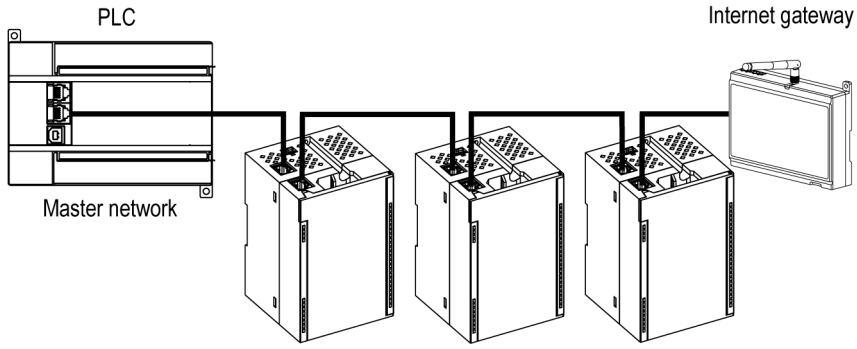


Fig. 5.6 Chain topology

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6 Factory settings restoration

NOTE
After restoring the factory settings all parameters but Ethernet will be reset to default values and the password deleted. The Ethernet parameters will not be affected.

To restore the factory settings:

1. Power on the device
2. Open the front cover
3. Using a thin tool, press and hold the service button (Fig. 2.2. Pos. 7) for at least 12 seconds
4. Close the cover

The device will operate with the default parameters.

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7 Maintenance

WARNING
Cut off all power before maintenance.

The maintenance includes:

– cleaning of the housing and terminal blocks from dust, dirt and debris
– checking the device fastening
– checking the wiring (connecting wires, terminal connections, absence of mechanical damages).

NOTICE
The device should be cleaned with a damp cloth only. No abrasives or solvent-containing cleaners may be used.

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8 Transportation and storage

Pack the device in such a way as to protect it reliably against impact for storage and transportation. The original packaging provides optimum protection.
If the device is not taken immediately after delivery into operation, it must be carefully stored at a protected location. The device should not be stored in an atmosphere with chemically active substances.
The environmental conditions from the Sect. 3.2 must be considered during transportation and storage.

NOTICE
The device may have been damaged during transportation.
Check the device for transport damage and completeness!
Report the transport damage immediately to the shipper and akYtec GmbH.

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9 Scope of delivery

–	MU210-412	1
–	Ethernet connection cable	1
–	2-pole plug-in terminal block	1
–	Rubber plug	1
–	Short guide	1

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MU210-412_3-EN-125356-1.5
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Appendix A. Dimensions

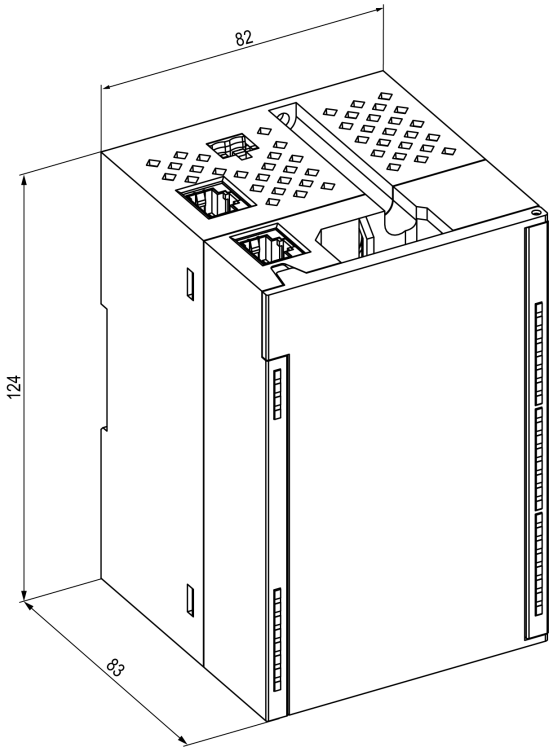


Fig. A.1

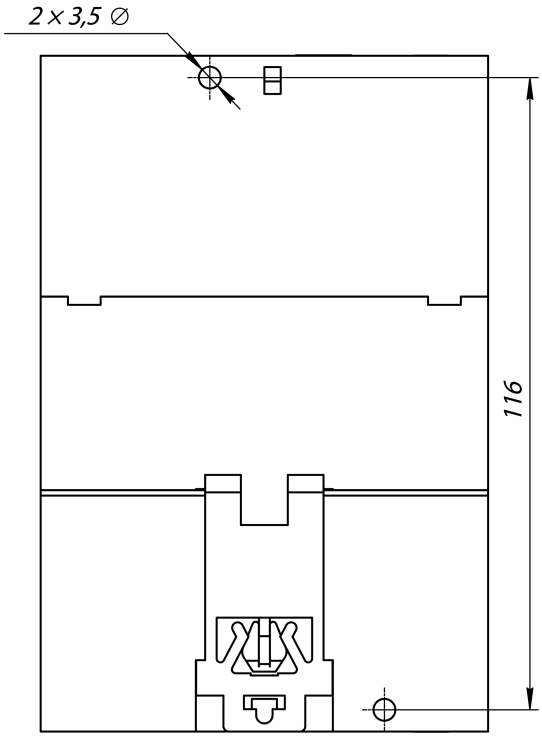


Fig. A.2

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Appendix B. Galvanic isolation

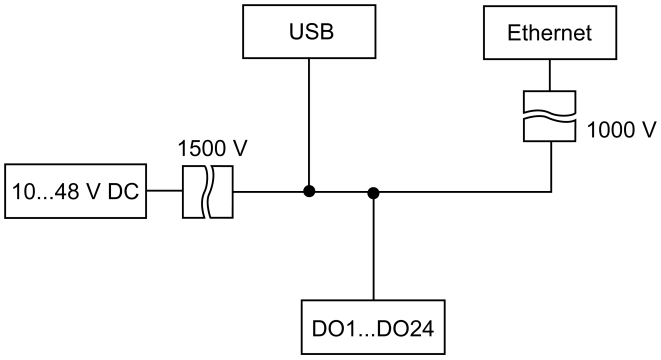


Fig. B.1 Galvanic isolation

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Appendix C. Battery replacement

To replace the battery, proceed as follows:

1. Power off the module and all connected devices
2. Remove the terminal blocks without disconnecting the connected wires (Fig. 5.2)
3. Remove the module from the DIN rail
4. Remove the front part the enclosure by opening the four side latches one-by-one using a flat screwdriver (Fig. C.1)
5. Replace the battery.

The replacement should not take longer than one minute. Otherwise, the real-time clock has to be adjusted anew.

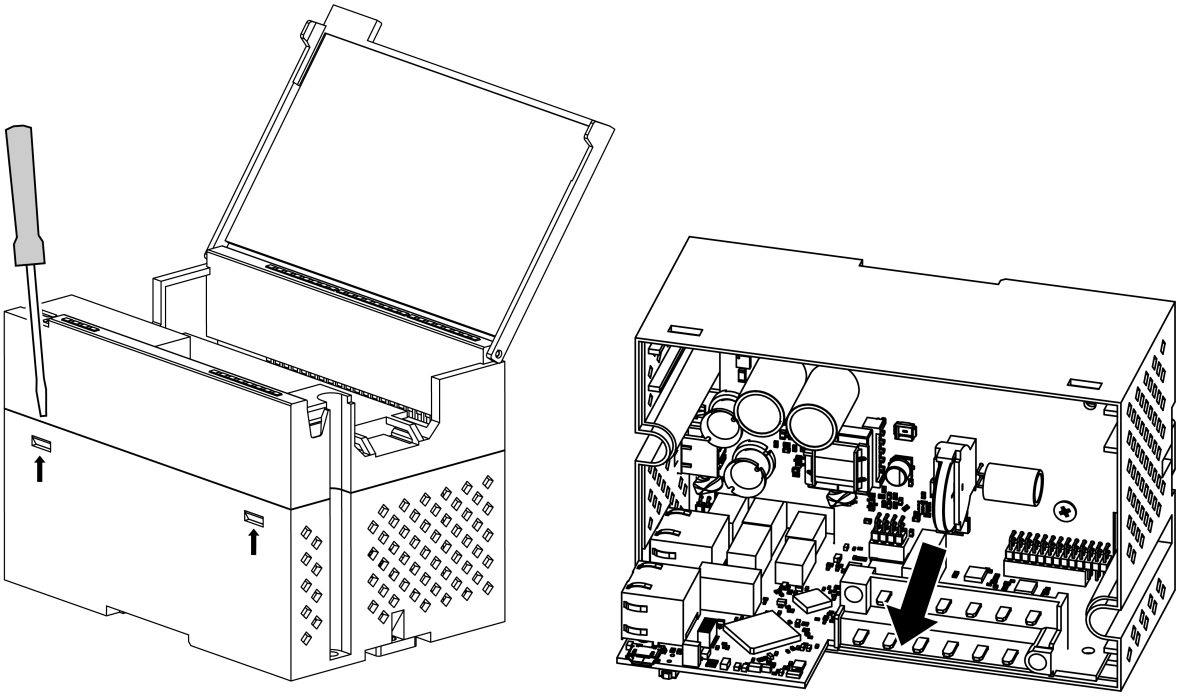


Fig. C.1 Battery replacement

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Appendix D. Modbus application

Table D.1 – device parameters with register addresses
Table D.2 – used data types
Table D.3 – used Modbus functions
Table D.4 – possible data exchange errors
Table D.5 – function-specific errors
If an error occurs when receiving a request, the module sends a response to the Master with an error code.
If the request does not comply with the Modbus specification, it will be ignored.

Table D.1 Modbus register

Parameter	Value	Unit	Access	Address		Data type
				hex	dec	
Device information						
Device name (dev)	—	—	R	0xF000	61440	String32
Firmware version (ver)	—	—	R	0xF010	61456	String32
Platform name	—	—	R	0xF020	61472	String32
Platform version	—	—	R	0xF030	61488	String32
Hardware version	—	—	R	0xF040	61504	String32
Additional text information	—	—	R	0xF048	61512	String32
S/N	—	—	R	0xF084	61572	String32
MAC address	—	—	R	0xF100	61696	UINT48
Real-time clock						
Time	—	s	R	0xF080	61568	DATETIME
Time zone	—	min	RW	0xF082	61570	TIMEZONE
Time (ms)	0…4294967295	ms	R	0xF07B	61563	UINT32
New time	—	s	RW	0xF07D	61565	DATETIME
Apply new time	0 – off / 1 – on	—	RW	0xF07F	61567	UINT16
Network / Ethernet						
IP address	—	—	R	0x001A	26	UINT32
Subnet mask	—	—	R	0x001C	28	UINT32
Gateway	—	—	R	0x001E	30	UINT32
DNS server 1	—	—	RW	0x000C	12	UINT32
DNS server 2	—	—	RW	0x000E	14	UINT32
New IP address	—	—	RW	0x0014	20	UINT32
New subnet mask	—	—	RW	0x0016	22	UINT32
New gateway	—	—	RW	0x0018	24	UINT32
DHCP	0 – off 1 – on 2 – service button	—	—	0x0020	26	UINT16
Battery						
Voltage	0…3300	mV	R	0x0321	801	UINT16
Modbus Slave						
Safe state timeout	0…60	s	RW	0x02BC	700	UINT8
Data logging						
Logging interval	10…3600	s	RW	0x0384	900	UINT16

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Parameter	Value	Unit	Ac-cess	Address		Data type
				hex	dec	
Digital outputs / Single						
DO1 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM 3 – pulse generator	—	RW	0x0110	272	UINT16
DO2 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM 3 – pulse generator	—	RW	0x0111	273	UINT16
DO3 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM 3 – pulse generator	—	RW	0x0112	274	UINT16
DO4 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM	—	RW	0x0113	275	UINT16
DO5 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM	—	RW	0x0114	276	UINT16
DO6 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM	—	RW	0x0115	277	UINT16
DO7 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM	—	RW	0x0116	278	UINT16
DO8 Control mode	0 – on /off 1 – low frequency PWM 2 – high frequency PWM	—	RW	0x0117	279	UINT16
DO9 Control mode	0 – on /off 1 – low frequency PWM	—	RW	0x0118	280	UINT16
…	…	…	…	…	…	…
DO24 Control mode	0 – on /off 1 – low frequency PWM	—	RW	0x0127	295	UINT16
DO1 Low frequency PWM period	1000…60000	ms	RW	0x0134	308	UINT16
…	…	…	…	…	…	…

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Parameter	Value	Unit	Ac-cess	Address		Data type
				hex	dec	
DO24 Low frequency PWM period	1000…60000	ms	RW	0x014B	331	UINT16
DO1 PWM duty cycle	0…1000	‰	RW	0x0154	340	UINT16
…	…	…	…	…	…	…
DO24 PWM duty cycle	0…1000	‰	RW	0x016B	363	UINT16
DO1 Pulse generator frequency	1…60000	Hz	RW	0x0174	372	UINT16
DO2 Pulse generator frequency	1…60000	Hz	RW	0x0175	373	UINT16
DO3 Pulse generator frequency	1…60000	Hz	RW	0x0176	374	UINT16
DO1 Pulse number to generate	0…65535	—	RW	0x0194	404	UINT16
DO2 Pulse number to generate	0…65535	—	RW	0x0195	405	UINT16
DO3 Pulse number to generate	0…65535	—	RW	0x0196	406	UINT16
DO1 safe state	0…1000	‰	RW	0x01DA	474	UINT16
…	…	…	…	…	…	…
DO24 safe state	0…1000	‰	RW	0x01F0	497	UINT16
DO1 High frequency PWM frequency	1…60000	Hz	RW	0x01FA	506	UINT16
…	…	…	…	…	…	…
DO8 High frequency PWM frequency	1…60000	Hz	RW	0x0201	513	UINT16
DO1 Number of left pulses	0…65535	—	R	0x021A	538	UINT16
DO2 Number of left pulses	0…65535	—	R	0x021B	539	UINT16
DO3 Number of left pulses	0…65535	—	R	0x021C	540	UINT16
Digital outputs / Group						
Output bitmask	0…16777215	—	R	0x01D4	468	UINT36
New output bitmask	0…16777215	—	RW	0x01D6	470	UINT32
NTP						
Enable	0 – off / 1 – on	—	RW	0x1600	5632	UINT16
NTP server pool	—	—	RW	0x1601	5633	String32
NTP server 1	—	—	RW	0x1641	5697	UINT32
NTP server 2	—	—	RW	0x1643	5699	UINT32
Synchronization period	5…65535	s	RW	0x1645	5701	UINT16
NTP status	0 – off 1 – on 2 – synchronized	—	RW	0x1646	5702	UINT16
MQTT						
Connect to broker	0 – off / 1 – on	—	RW	0x1700	5888	UINT16
User name	—	—	RW	0x1728	5928	String32
Password	—	—	RW	0x1748	5960	String32
Device name	—	—	RW	0x1708	5896	String32
Broker address	—	—	RW	0x1769	5993	String32
Port	0…65535	—	RW	0x1703	5891	UINT16
Store last message	0 – off / 1 – on	—	RW	0x1707	5895	UINT16
Publishing interval	5…600	s	RW	0x1704	5892	UINT16
Quality of service	0 – QoS0	—	RW	0x1705	5893	UINT16

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Parameter	Value	Unit	Access	Address		Data type
				hex	dec	
	1 – QoS1 2 – QoS2					
Keep Alive	0…600	s	RW	0x1768	5992	UINT16
Status	0 – off 1 – on 2 – connection error	—	R	0x1789	6025	UINT16
Enable	0 – off / 1 – on	—	RW	0x178A	6026	UINT16
SNMP						
Enable	0 – off / 1 – on	—	RW	0x1400	5120	UINT16
Read community	—	—	RW	0x1771	6001	String32
Write community	—	—	RW	0x1781	6017	String32
Trap IP address	—	—	RW	0x1401	5121	UINT32
Trap port	0…65535	—	RW	0x1403	5123	UINT16
SNMP version	0 – SNMPv1 1 – SNMPv2	—	RW	0x1404	5124	UINT16

Table D.2 Data types

Data type	Size (registers)	Size (bytes)	Description
UINT8	1	1	Unsigned integer
UINT16	1	2	Unsigned integer
UINT32	2	4	Unsigned integer
UINT48	3	6	Unsigned integer
INT16	1	2	Signed integer
String16	8	16	String of characters (Win-1251 code page)
String32	16	32	String of characters (Win-1251 code page)
DATETIME	2	4	UINT32, time in seconds, starting from 01/01/2000, 00:00
TIMEZONE	1	2	INT16, difference between UTC and local time in minutes

Table D.3 Modbus functions

Code	Name	Description
03 (0x03)	Read Holding Registers	Read the contents of a contiguous block of holding register
04 (0x04)	Read Input Registers	Read from 1 to 125 contiguous input registers
06 (0x06)	Write Single Register	Write a single holding register
16 (0x10)	Write Multiple Registers	Write a block of contiguous registers (1 to 123 registers)
20 (0x14)	Read File Record	Read file as a set of records
21 (0x15)	Write File Record	Write file as a set of records

Table D.4 Modbus error codes

Code	Name	Description
01	Illegal Function	The received function code is not recognized or accepted by slave
02	Illegal Data Address	Data address of some or all the required entities are not allowed or do not exist in slave
03	Illegal Data Value	Value is not accepted by slave
04	Slave Device Failure	Unrecoverable error occurred while slave was attempting to perform requested action

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Table D.5 Function-specific errors

Function code	Error code	Possible error causes
03	02	Number of requested registers is greater than the maximum possible (125)
		Nonexistent parameter request
04	02	Number of requested registers is greater than the maximum possible (125)
		Request for a nonexistent parameter
06	02	An attempt to write a parameter longer than 2 bytes
		An attempt to write a read-only parameter
		An attempt to write a parameter of a type not supported by this function. Supported types: – INT, UINT, max. 2 bytes – enumerated – REAL16
		Nonexistent parameter requested
	03	Parameter value is beyond the valid limits
16	02	Nonexistent parameter requested
		An attempt to write a read-only parameter
		Number of requested registers is greater than the maximum possible (123)
	03	No termination character (\0) in string parameter
		Size of the requested data is less than the size of the first or last parameter in the request
		Parameter value is beyond the valid limits
20	01	Invalid data size (valid range 0x07…0xF5)
	02	Not specified reference type
		Failed to open the file for reading (may be nonexistent)
	03	Failed to move to the desired offset in the file
	04	Error while deleting file on delete request
		Too much data requested (more than 250 bytes)
		Invalid record number (greater than 0x270F)
		Invalid record length (greater than 0x7A)
21	01	Invalid data size (valid range 0x09…0xFB)
	02	Not specified reference type
		Failed to open the file for writing
	04	Nonexistent file requested
		Read-only file requested
		Failed to write the required number of bytes

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